


NEW ESTIMATES FOR THE SCALAR CURVATURE OF COMPLETE MINIMAL HYPERSURFACES IN \mathbb{S}^4

A. C. Asperti R. M. B. Chaves
L. A. M. Sousa, Jr. 

Dedicated to Professor Manfredo do Carmo on the occasion of his 80th birthday

Abstract

Let M^3 be a complete minimal hypersurface immersed in the unit sphere \mathbb{S}^4 . In this paper, starting from hypotheses on the Gauss-Kronecker curvature we obtain estimates for the scalar curvature of M^3 .

1 Introduction

Denote by \mathbb{S}^N the N -dimensional unit sphere in \mathbb{R}^{N+1} . Let M^n be an n -dimensional submanifold minimally immersed in \mathbb{S}^{n+p} . Denote by R the scalar curvature of M^n and by S the square of the length of the second fundamental form of M^n . In his celebrated paper, J. Simons [6] obtained the following inequality for the Laplacian of S

$$\frac{1}{2}\Delta S \geq S \left(n - \left(2 - \frac{1}{p} \right) S \right). \quad (1.1)$$

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As an application of (1.1), Simons proved that if M^n is closed then either M^n is totally geodesic, or $S = \frac{n}{2-1/p}$, or $\sup S > \frac{n}{2-1/p}$. In this paper we prove an inequality similar to that of Simons given above for complete minimal hypersurfaces in \mathbb{S}^4 .

Theorem 1.1. *Let M^3 be a complete minimal hypersurface in \mathbb{S}^4 . Let K be the Gauss-Kronecker curvature of M^3 . If S is bounded and $|K|$ is bounded away from zero, then $\inf S \leq 3 \leq \sup S$.*

The inequality $\sup S \geq 3$ is a particular case of one established by Cheng in [1] that extended Simons' result, for complete submanifolds. We point out that, although for $p = 1$ the sharp estimate $S \geq n$ was due to Simons, the characterization of the hypersurfaces satisfying $S = n$ was obtained independently by Chern, Do Carmo and Kobayashi [2] and Lawson [3]. Up to now, it is not known if there exist complete minimal hypersurfaces satisfying $\sup S = n$ and that are not congruent to the Clifford tori $\mathbb{S}^k \left(\sqrt{\frac{k}{n}} \right) \times \mathbb{S}^{n-k} \left(\sqrt{\frac{n-k}{n}} \right)$.

By the fact that $R = 6 - S$, in case $n = 3$, see (2.4), we immediately obtain the following consequence of Theorem 1.1.

Corollary 1.1. *Let M^3 be a complete minimal hypersurface in \mathbb{S}^4 . If R is bounded and $|K|$ is bounded away from zero, then $\inf R \leq 3 \leq \sup R$.*

Remark 1.1. *By using similar arguments to the ones used in this paper, the authors already obtained a classification of complete minimal hypersurfaces with constant Gauss-Kronecker curvature in a four dimensional space form. The results will appear in a forthcoming paper.*

2 Preliminaries and Notations

Let M^3 be a 3-dimensional hypersurface in a unit sphere \mathbb{S}^4 . We choose a local orthonormal frame field $\{e_1, \dots, e_4\}$ in \mathbb{S}^4 , so that, restricted to M^3 , e_1, e_2, e_3 are tangent to M^3 . Let $\{\omega_1, \dots, \omega_4\}$ denote the dual co-frame field in \mathbb{S}^4 . We use the following convention for the range of the indices: A, B, C, D range from 1 to 4 and i, j, k range from 1 to 3. The structure equations of \mathbb{S}^4 are given by

$$d\omega_A = -\sum_B \omega_{AB} \wedge \omega_B, \quad \omega_{AB} + \omega_{BA} = 0,$$

$$d\omega_{AB} = -\sum_C \omega_{AC} \wedge \omega_{CB} + \frac{1}{2} \sum_{C,D} K_{ABCD} \omega_C \wedge \omega_D,$$

where $K_{ABCD} = \delta_{AC}\delta_{BD} - \delta_{AD}\delta_{BC}$ is the curvature tensor of \mathbb{S}^4 . Since $\omega_4 = 0$ on M^3 , by *Cartan's Lemma* we have

$$\omega_{4i} = \sum_j h_{ij} \omega_j, \quad h_{ij} = h_{ji}. \quad (2.1)$$

We call $h = \sum_{i,j} h_{ij} \omega_i \omega_j$, the eigenvalues λ_i of the matrix (h_{ij}) , $H = \sum_i h_{ii} = \sum_i \lambda_i$ and $K = \det(h_{ij}) = \prod_i \lambda_i$, respectively, the *second fundamental form*, the *principal curvatures*, the *mean curvature* and the *Gauss-Kronecker curvature* of M^3 .

The structure equations of M^3 are given by

$$\begin{aligned} d\omega_i &= -\sum_j \omega_{ij} \wedge \omega_j, \quad \omega_{ij} + \omega_{ji} = 0, \\ d\omega_{ij} &= -\sum_k \omega_{ik} \wedge \omega_{kj} + \frac{1}{2} \sum_{k,\ell} R_{ijkl} \omega_k \wedge \omega_\ell. \end{aligned}$$

Using the formulas above we obtain the Gauss equation

$$R_{ijkl} = K_{ijkl} + h_{ik}h_{jl} - h_{il}h_{jk}. \quad (2.2)$$

We recall that M^3 is a *minimal* hypersurface if its mean curvature is identically zero. From now on, we assume that M^3 is minimal. In this situation, its Ricci curvature tensor and scalar curvature are given, respectively, by

$$R_{ij} = 2\delta_{ij} - \sum_k h_{ik}h_{jk}, \quad (2.3)$$

$$R = 6 - S, \quad \text{where} \quad S = \sum_{i,j} h_{ij}^2 \text{ is the squared norm of } h. \quad (2.4)$$

It follows from (2.4) that R is constant if and only if S is constant.

The covariant derivative ∇h of the second fundamental form h of M^3 with components h_{ijk} is given by

$$\sum_k h_{ijk}\omega_k = dh_{ij} + \sum_k h_{jk}\omega_{ik} + \sum_k h_{ik}\omega_{jk}.$$

Then the exterior derivative of (2.1) together with the structure equations yields the Codazzi equation

$$h_{ijk} = h_{ikj} = h_{jik}. \quad (2.5)$$

Hence h_{ijk} is symmetric on the indices i, j, k .

Similarly, we have the second covariant derivative $\nabla^2 h$ of h with components h_{ijkl} as follows

$$\sum_\ell h_{ijkl}\omega_\ell = dh_{ijk} + \sum_\ell h_{\ell jk}\omega_{i\ell} + \sum_\ell h_{i\ell k}\omega_{j\ell} + \sum_\ell h_{ij\ell}\omega_{k\ell}.$$

For any fixed point p on M^3 , we can choose a local orthonormal frame field $\{e_1, e_2, e_3\}$ such that

$$h_{ij} = \lambda_i \delta_{ij}.$$

The following formulas can be found in Peng and Terng [5].

$$h_{ijij} - h_{jiji} = (\lambda_i - \lambda_j)(1 + \lambda_i \lambda_j). \quad (2.6)$$

$$\Delta h_{ij} = (3 - S)h_{ij}. \quad (2.7)$$

$$\frac{1}{2}\Delta S = \sum_{i,j,k} h_{ijk}^2 + (3 - S)S. \quad (2.8)$$

The proof of our results relies heavily on the well known *Generalized Maximum Principle* due to H. Omori [4].

Lemma 2.1. *Let M^n be an n -dimensional complete Riemannian manifold whose sectional curvature is bounded from below and $f : M^n \rightarrow \mathbb{R}$ be a smooth function which is bounded from above on M^n . Then there is a sequence of points $\{p_k\}$ in M^n such that*

$$\lim_{k \rightarrow \infty} f(p_k) = \sup f; \quad \lim_{k \rightarrow \infty} |\nabla f(p_k)| = 0 \text{ and}$$

$$\limsup_{k \rightarrow \infty} \max\{(Hess_f(p_k))(X, X) : |X| = 1\} \leq 0,$$

where $Hess_f$ denotes the Hessian of f .

3 Proof of Theorem 1.1

The inequality $\sup S \geq 3$ is a particular case of the one established by Cheng in [1]. For reader's convenience we shall prove it here. Let us assume on the contrary that $\sup S < 3$. As S is bounded from (2.2) we see that the sectional curvatures are bounded from below. So, by using Lemma 2.1 we obtain a sequence $\{p_k\}$ of points in M^3 such that

$$\begin{aligned} \lim_{k \rightarrow \infty} S(p_k) = \sup S; \quad \lim_{k \rightarrow \infty} |\nabla S(p_k)| = 0 \\ \text{and } \limsup_{k \rightarrow \infty} (S_{ii}(p_k)) \leq 0. \end{aligned} \quad (3.1)$$

By evaluating (2.8) at p_k and taking the limit for $k \rightarrow \infty$, from (3.1) we arrive to

$$\sup S(3 - \sup S) \leq \limsup_{k \rightarrow \infty} \frac{1}{2} \Delta S(p_k) \leq \frac{1}{2} \sum_i \limsup_{k \rightarrow \infty} S_{ii}(p_k) \leq 0. \quad (3.2)$$

This implies that $\sup S = 0$, i.e., M^3 is totally geodesic which contradicts our hypothesis that $|K|$ is bounded away from zero. Hence, we have $\sup S \geq 3$.

Now let us prove the inequality $\inf S \leq 3$. As K does not vanish, the function $F = \log |\det(h_{ij})|$ is globally defined on M^3 and is smooth. For any fixed point $p \in M^3$ we can take a local orthonormal frame field $\{e_1, e_2, e_3\}$ such that $h_{ij} = \lambda_i \delta_{ij}$ at p . According to Peng-Terng (see [5] pp 15) the Laplacian of F is given by

$$\Delta F = - \sum_{ijk} \frac{1}{\lambda_i \lambda_j} h_{ijk}^2 + \sum_{ik} \frac{1}{\lambda_i} h_{iikk}. \quad (3.3)$$

Since M^3 is minimal, we have $\sum_k h_{kkii} = H_{ii} = 0$, for all i . Together with (2.6) this gives

$$\begin{aligned} \sum_{ik} \frac{1}{\lambda_i} h_{iikk} &= \sum_{ik} \frac{1}{\lambda_i} [h_{kkii} + (\lambda_i - \lambda_k)(1 + \lambda_i \lambda_k)] = \\ \sum_{ik} \frac{1}{\lambda_i} (\lambda_i - \lambda_k)(1 + \lambda_i \lambda_k) &= 3(3 - S) = -3(S - 3). \end{aligned} \quad (3.4)$$

Notice that *Codazzi equation* (2.5) yields

$$\frac{1}{\lambda_i \lambda_j} h_{ijk}^2 = \frac{1}{\lambda_j \lambda_i} h_{jik}^2.$$

Then the coefficient of h_{123}^2 in $\sum_{ijk} \frac{1}{\lambda_i \lambda_j} h_{ijk}^2$ can be given by

$$2 \left(\frac{1}{\lambda_1 \lambda_2} + \frac{1}{\lambda_1 \lambda_3} + \frac{1}{\lambda_2 \lambda_3} \right) = \frac{2H}{K} = 0$$

and we may write

$$\sum_{ijk} \frac{1}{\lambda_i \lambda_j} h_{ijk}^2 = \sum_i \sum_{j \neq i, k \neq i, j < k} \left[\frac{1}{\lambda_i^2} h_{iii}^2 + \left(\frac{1}{\lambda_j^2} + \frac{2}{\lambda_i \lambda_j} \right) h_{jji}^2 + \left(\frac{1}{\lambda_k^2} + \frac{2}{\lambda_i \lambda_k} \right) h_{kki}^2 \right]. \quad (3.5)$$

Let i, j, k be pairwise distinct indices. Bearing in mind that M^3 is minimal, we have $\lambda_i + \lambda_j = -\lambda_k$, $\lambda_i + \lambda_k = -\lambda_j$ and $h_{iii} = -(h_{jji} + h_{kki})$ which implies

$$\begin{aligned} & \frac{1}{\lambda_i^2} h_{iii}^2 + \left(\frac{1}{\lambda_j^2} + \frac{2}{\lambda_i \lambda_j} \right) h_{jji}^2 + \left(\frac{1}{\lambda_k^2} + \frac{2}{\lambda_i \lambda_k} \right) h_{kki}^2 = \\ & \frac{1}{\lambda_i^2} (h_{jji} + h_{kki})^2 + \left(\frac{1}{\lambda_j^2} + \frac{2}{\lambda_i \lambda_j} \right) h_{jji}^2 + \left(\frac{1}{\lambda_k^2} + \frac{2}{\lambda_i \lambda_k} \right) h_{kki}^2 = \\ & \left(\frac{1}{\lambda_i^2} + \frac{2}{\lambda_i \lambda_j} + \frac{1}{\lambda_j^2} \right) h_{jji}^2 + \left(\frac{1}{\lambda_i^2} + \frac{2}{\lambda_i \lambda_k} + \frac{1}{\lambda_k^2} \right) h_{kki}^2 + \\ & \frac{2}{\lambda_i^2} h_{jji} h_{kki} = \left(\frac{1}{\lambda_i} + \frac{1}{\lambda_j} \right)^2 h_{jji}^2 + \left(\frac{1}{\lambda_i} + \frac{1}{\lambda_k} \right)^2 h_{kki}^2 + \frac{2}{\lambda_i^2} h_{jji} h_{kki} = \\ & \frac{\lambda_k^2}{\lambda_i^2 \lambda_j^2} h_{jji}^2 + \frac{\lambda_j^2}{\lambda_i^2 \lambda_k^2} h_{kki}^2 + \frac{2}{\lambda_i^2} h_{jji} h_{kki} = \frac{1}{K^2} (\lambda_k^2 h_{jji} + \lambda_j^2 h_{kki})^2. \end{aligned} \quad (3.6)$$

Inserting (3.6) into (3.5) we obtain

$$\sum_{ijk} \frac{1}{\lambda_i \lambda_j} h_{ijk}^2 = \frac{1}{K^2} \left[(\lambda_3^2 h_{221} + \lambda_2^2 h_{331})^2 + (\lambda_3^2 h_{112} + \lambda_1^2 h_{332})^2 + (\lambda_2^2 h_{113} + \lambda_1^2 h_{223})^2 \right]. \quad (3.7)$$

It follows from (3.3), (3.4) and (3.7) that

$$\Delta F = -\frac{1}{K^2} \left[(\lambda_3^2 h_{221} + \lambda_2^2 h_{331})^2 + (\lambda_3^2 h_{112} + \lambda_1^2 h_{332})^2 + (\lambda_2^2 h_{113} + \lambda_1^2 h_{223})^2 \right] - 3(S - 3). \quad (3.8)$$

As S is bounded, we have already seen that the sectional curvatures of M^3 are bounded from below. Further, since $|K|$ is bounded away from zero, $F = \log |\det(h_{ij})|$ is bounded from below, so we may apply the *Generalized Maximum Principle due to Omori* to the function F to obtain a sequence $\{p_k\}$ of points in M^3 such that

$$\begin{aligned} \lim_{k \rightarrow \infty} F(p_k) &= \inf F; \quad \lim_{k \rightarrow \infty} |\nabla F(p_k)| = 0 \\ &\text{and } \liminf_{k \rightarrow \infty} (F_{ii}(p_k)) \geq 0. \end{aligned} \quad (3.9)$$

In view of (3.8) we get the inequality

$$\Delta F \leq -3(S - 3). \quad (3.10)$$

Evaluating (3.10) at $\{p_k\}$ and making $k \rightarrow \infty$, from (3.9) we obtain

$$0 \leq \sum_i \liminf_{k \rightarrow \infty} F_{ii}(p_k) \leq \Delta F \leq \liminf_{k \rightarrow \infty} 3(3 - S(p_k)). \quad (3.11)$$

From (3.11) we deduce that $\inf S \leq 3$, which completes our proof. \square

Remark 3.1. *We would like to emphasize that the hypothesis that $|K|$ is bounded away from zero cannot be dropped, as shows the following example.*

Example 3.1. *The hypersurface M^3 in \mathbb{S}^4 defined by the equation*

$$2x_5^3 + 3(x_1^2 + x_2^2)x_5 - 6(x_3^2 + x_4^2)x_5 + 3\sqrt{3}(x_1^2 - x_2^2)x_4 + 6\sqrt{3}x_1x_2x_3 = 2$$

was investigated by E. Cartan, who proved that this space is a homogeneous Riemannian manifold $SO(3)/(\mathbb{Z}_2 \times \mathbb{Z}_2)$ and that its principal curvatures are $-\sqrt{3}, 0, \sqrt{3}$. Therefore, M^3 has $\inf S = S = 6$.

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Instituto de Matemática e
Estatística
Univ. de São Paulo
Rua do Matão, 1010
05508-090, São Paulo-SP, Brazil
E-mail: asperti@ime.usp.br
E-mail: rosab@ime.usp.br

Departamento de Matemática e
Estatística
Univ. Federal do Estado do
Rio de Janeiro
Avenida Pasteur, 458, Urca
22290-240, Rio de Janeiro-RJ, Brazil
E-mail: amancio@impa.br